

Chapter 2: Orthogonality & isotropy

Exercise 3. Let *E* be a \mathbb{R} -vector space of dimension $n < \infty$. Determine all $\varphi \in \mathcal{S}(E)$ (*i.e.* symmetric bilinear forms) such that $n = \dim \ker(\varphi) + 1$.

Solution of exercise 3. rank(φ) = 1, for

$$\mathcal{J}_{\varphi}: E \longrightarrow E^{\star}$$
$$u \longmapsto j_{u},$$

we have $\operatorname{Ker}(\varphi) = \operatorname{Ker} \mathscr{J}_{\varphi}$ has a basis consisting of n-1 vectors, say u_2, \ldots, u_n . Let $u_1 \notin \operatorname{Ker}(\mathscr{J}_{\varphi})$, let $c = q(u_1)$. We have $c \neq 0$ since $\varphi \neq 0$. Define $\ell_1(u_i) = \delta_{i1}, \ell_2(u_i) = \delta_{i1}c$, then $\varphi(u, v) = \ell_1(u)\ell_2(v)$.

Exercise 4. Let *E* be the vector space:

$$E := \left\{ \left(\begin{array}{cc} a & b \\ c & d \end{array} \right) \in \mathbf{M}_2(\mathbb{R}) : a - d = \mathbf{o} \right\}$$

Let also $J := \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix}$ and define $q : E \longrightarrow \mathbb{R}$ by

$$q(A) := \operatorname{Tr}(AJA), \quad A \in E.$$

- 1. Prove *q* is a quadratic form and determine its polar form.
- 2. Prove that $\mathscr{B} := \left(\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}, \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix} \right)$ is a basis of *E*,
- 3. Give the matrix of q in the basis \mathcal{B} .
- 4. Determine the rank, the kernel and the signature of *q*. Is it positive? negative? definite?
- 5. Determine the orthogonal for q of Span (I_2).

Solution of exercise 4.

- 1. $q(\lambda A) = \operatorname{Tr}(\lambda^2 A J A) = \lambda^2 \operatorname{Tr}(A J A)$. $\varphi_q(A_1, A_2) = \frac{1}{2} (\operatorname{Tr}((A_1 + A_2)J(A_1 + A_2)) \operatorname{Tr}(A_1 J A_1) \operatorname{Tr}(A_2 J A_2)) = \frac{1}{2} (\operatorname{Tr}(A_1 J A_2) + \operatorname{Tr}(A_2 J A_1))$. φ_q is symmetric and bilinear.
- 2. Easy to check.
- 3. Set $v_1 := E_{11} + E_{22} = \text{Id}$, $v_2 := E_{12}$ and $v_3 := E_{21}$. Then $\varphi_q(v_1, v_1) = 0$, $\varphi_q(v_1, v_2) = 1$, $\varphi_q(v_1, v_3) = 1$; $\varphi_q(v_2, v_2) = 0$, $\varphi_q(v_2, v_3) = 0$; $\varphi_q(v_3, v_3) = 0$. We have $\mathscr{M}_{\mathscr{B}}(\varphi_q)$ is the following:

$$\begin{pmatrix}
0 & 1 & 1 \\
1 & 0 & 0 \\
1 & 0 & 0
\end{pmatrix}$$



4.
$$\operatorname{rank}(q) = \operatorname{rank}(\mathscr{M}_{\mathscr{B}}(\varphi_q)) = 2$$
. $\operatorname{Ker}(q) = \{u \in E \mid \varphi_q(u, v) = 0 \; \forall v \in E\}, \operatorname{Ker}(q) = \operatorname{Span}_{\mathbb{R}}(v_2 - v_3)$. Let $v = x_1v_1 + x_2v_2 + x_3v_3$, then $\varphi_q(v, v)_{\mathscr{B}} = (x_1 x_2 x_3) \begin{pmatrix} 0 & 1 & 1 \\ 1 & 0 & 0 \\ 1 & 0 & 0 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = 2x_1(x_2 + x_3) = \frac{1}{2}[(x_1 + x_2 + x_3)^2 - (x_1 - x_2 - x_3)^2]$.
It has signature (1, 1) thus not definite.
5. $\operatorname{Span}(\operatorname{Id})^{\perp} = \operatorname{Span}(v_1)^{\perp} = \{v \in E \mid \varphi_q(v, v_1) = 0\}. \; \varphi_q(v, v_1)_{\mathscr{B}} = (x_1 x_2 x_3) \begin{pmatrix} 0 & 1 & 1 \\ 1 & 0 & 0 \\ 1 & 0 & 0 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} = x_2 + x_3 = 0$, thus $\operatorname{Span}(v_1)^{\perp} = \operatorname{Span}(v_2 - v_3, v_1)$.

Remark. **Question**: Which step has problem in the following: By the standard process of finding the eigenspaces, we have

$$\begin{pmatrix} 0 & 1 & 1 \\ 1 & 0 & 0 \\ 1 & 0 & 0 \end{pmatrix} = PJ^{t}P \quad \text{where} \quad P = \begin{pmatrix} 0 & -\sqrt{2}/2 & \sqrt{2}/2 \\ -1/\sqrt{2} & 1/2 & 1/2 \\ 1/\sqrt{2} & 1/2 & 1/2 \end{pmatrix} =: (u_{1}, u_{2}, u_{3}), \quad J = \begin{pmatrix} 0 & 0 & 0 \\ 0 & -\sqrt{2} & 0 \\ 0 & 0 & \sqrt{2} \end{pmatrix},$$
$$q(a_{1}u_{1} + a_{2}u_{2} + a_{3}u_{3}) = (a_{1}, a_{2}, a_{3})^{t}P\mathscr{M}_{\mathscr{B}}(\varphi_{q})P \begin{pmatrix} a_{1} \\ a_{2} \\ a_{3} \end{pmatrix} = -\sqrt{2}a_{2}^{2} + \sqrt{2}a_{3}^{2}, \text{ replace } u_{2} \text{ by } \sqrt[4]{2}u_{2}, u_{3} \text{ by } \sqrt[4]{2}u_{3}, \text{ then } q(a_{1}u_{1} + a_{2}u_{2} + a_{3}u_{3}) = (a_{1}, a_{2}, a_{3})^{t}P\mathscr{M}_{\mathscr{B}}(\varphi_{q})P \begin{pmatrix} a_{1} \\ a_{2} \\ a_{3} \end{pmatrix} = -\sqrt{2}a_{2}^{2} + \sqrt{2}a_{3}^{2}, \text{ replace } u_{2} \text{ by } \sqrt[4]{2}u_{2}, u_{3} \text{ by } \sqrt[4]{2}u_{3}, \text{ then } q(a_{1}u_{1} + a_{2}u_{2} + a_{3}u_{3}) = (a_{1}, a_{2}, a_{3})^{t}P\mathscr{M}_{\mathscr{B}}(\varphi_{q})P \begin{pmatrix} a_{1} \\ a_{2} \\ a_{3} \end{pmatrix} = -\sqrt{2}a_{2}^{2} + \sqrt{2}a_{3}^{2}, \text{ replace } u_{2} \text{ by } \sqrt[4]{2}u_{2}, u_{3} \text{ by } \sqrt[4]{2}u_{3}, \text{ then } q(a_{1}u_{1} + a_{2}u_{2} + a_{3}u_{3}) = (a_{1}, a_{2}, a_{3})^{t}P\mathscr{M}_{\mathscr{B}}(\varphi_{q})P \begin{pmatrix} a_{1} \\ a_{2} \\ a_{3} \end{pmatrix} = -\sqrt{2}a_{2}^{2} + \sqrt{2}a_{3}^{2}, \text{ replace } u_{2} \text{ by } \sqrt[4]{2}u_{2}, u_{3} \text{ by } \sqrt[4]{2}u_{3}, \text{ then } q(a_{1}u_{1} + a_{2}u_{2} + a_{3}u_{3}) = (a_{1}, a_{2}, a_{3})^{t}P\mathscr{M}_{\mathscr{B}}(\varphi_{q})P \begin{pmatrix} a_{1} \\ a_{2} \\ a_{3} \end{pmatrix} = -\sqrt{2}a_{2}^{2} + \sqrt{2}a_{3}^{2}, \text{ replace } u_{2} \text{ by } \sqrt[4]{2}u_{3}, \text{ by } \sqrt[4]{2}u_{3}, \text{ then } q(a_{1}u_{1} + a_{2}u_{2} + a_{3}u_{3}) = (a_{1}, a_{2}, a_{3})^{t}P\mathscr{M}_{\mathscr{B}}(\varphi_{q})P \begin{pmatrix} a_{1} \\ a_{2} \\ a_{3} \end{pmatrix} = -\sqrt{2}a_{2}^{2} + \sqrt{2}a_{3}^{2}, \text{ replace } u_{3} \text{ by } \sqrt[4]{2}u_{3}, \text{ by } \sqrt[4]{2}u_{3}, \text{ by } \sqrt[4]{2}u_{3} \end{pmatrix} = (a_{1}, a_{2}, a_{3})^{t}P\mathscr{M}_{\mathscr{B}}(\varphi_{q})P \begin{pmatrix} a_{1} \\ a_{2} \\ a_{3} \end{pmatrix} = (a_{1}, a_{2}, a_{3})^{t}P\mathscr{M}_{\mathscr{B}}(\varphi_{q})P \begin{pmatrix} a_{1} \\ a_{2} \\ a_{3} \end{pmatrix} = (a_{1}, a_{2}, a_{3})^{t}P\mathscr{M}_{\mathscr{B}}(\varphi_{q})P \begin{pmatrix} a_{1} \\ a_{2} \\ a_{3} \end{pmatrix} = (a_{1}, a_{2}, a_{3})^{t}P \begin{pmatrix} a_{2} \\ a_{3} \end{pmatrix} = (a_{1}, a_{2}, a_{3})^{t}P \begin{pmatrix} a_{2} \\ a_{3} \end{pmatrix} = (a_{1}, a_{2}, a_{3})^{t}P \begin{pmatrix} a_{2} \\ a_{3} \end{pmatrix} = (a_{1}, a_{2}, a_{3})^{t}P \begin{pmatrix} a_{2} \\ a_{3} \end{pmatrix} = (a_{1}, a_{2}, a_{3})^{t}P \begin{pmatrix} a_{2} \\ a_{3} \end{pmatrix} = (a_{1}, a_$$

 $a_2u'_2 + a_3u'_3) = -a_2^2 + a_3^3$. *q* has signature (1, 1), and it is not definite. *Exercise 9.* Consider the quadratic form *q* on **C**³ defined by

$$q(u_1, u_2, u_3, u_4) = u_1 u_2 + u_2 u_4 - u_3 u_4 - 2u_1 u_4 - 2u_2 u_3 - u_1 u_3.$$

- 1. Prove, without reducing q, that q has maximal rank,
- 2. Give an orthogonal basis for *q*.

Solution of exercise 9.

1. The associated matrix is
$$\begin{pmatrix} 0 & \frac{1}{2} & -\frac{1}{2} & -1 \\ \frac{1}{2} & 0 & -1 & \frac{1}{2} \\ -\frac{1}{2} & -1 & 0 & -\frac{1}{2} \\ -1 & \frac{1}{2} & -\frac{1}{2} & 0 \end{pmatrix}$$

2.
$$q(u_1, u_2, u_3, u_4) = u_1 u_2 + u_2 u_4 - u_3 u_4 - 2u_1 u_4 - 2u_2 u_3 - u_1 u_3$$
$$= u_1 (u_2 - u_3 - 2u_4) + u_2 u_4 - u_3 u_4 - 2u_2 u_3$$
$$= -\frac{1}{2} u_1^2 + \frac{1}{2} (u_1 + u_2 - u_3 - 2u_4)^2 - \frac{1}{2} (u_2 - u_3 - 2u_4)^2 + u_2 u_4 - u_3 u_4 - 2u_2 u_3$$
(1)

Exercise 10. Let *E* be a \mathbb{R} -vector space of dimension $n \ge 2$ and $f_1, f_2 \in E^*$ be linearly independent. Let $q: E \to \mathbb{R}$ be defined by $q(u) = f_1(u)f_2(u)$ for all $u \in E$.



- 1. Show q is a quadratic form on E,
- 2. Determine the rank and the signature of *q*.

Solution of exercise 10.

1. $\varphi_q(u,v) = \frac{1}{2}(f_1(u+v)f_2(u+v) - f_1(u)f_2(u) - f_1(v)f_2(v)) = \frac{1}{2}(f_1(u)f_2(v) + f_1(v)f_2(u))$. The rest are easy to check.

2.
$$q = \frac{1}{4}((f_1 + f_2)^2 - (f_1 - f_2)^2)$$
. Set $\ell_1 := f_1 + f_2$, $\ell_2 = f_1 - f_2$, $(f_1 \ f_2) = A(e_1^* \ e_2^*)$ then $(\ell_1 \ \ell_2) = \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} A(e_1^* \ e_2^*)$, since f_1 , f_2 are linearly independent, A is invertible, thus $\begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} A$ invertible and ℓ_1, ℓ_2 are linearly independent. Therefore q has signature $(1, 1)$ and rank 2.

Exercise 11. Let $q \in \mathcal{Q}(\mathbb{R}^3)$ which matrix in the canonical basis of \mathbb{R}^3 is

$$\left(\begin{array}{rrrr} 1 & 1 & 1 \\ 1 & 2 & 3 \\ 1 & 3 & 5 \end{array}\right).$$

- 1. Determine the rank and the kernel of q,
- 2. What is the signature of q ?
- 3. Determine a basis of the orthogonal of G := Span((0, 1, 0), (1, 0, 1)). Do we have $\mathbb{R}^3 = G \oplus G^{\perp}$?

Solution of exercise 11.

1.
$$\varphi_q(v, v)_{\text{canonical basis}} = (x_1 \ x_2 \ x_3) \begin{pmatrix} 1 & 1 & 1 \\ 1 & 2 & 3 \\ 1 & 3 & 5 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = x_1^2 + 2x_1x_2 + 2x_1x_3 + 6x_2x_3 + 2x_2^2 + 5x_3^2 = \dots = (x_1 + x_2 + x_3)^2 + (x_2 + 2x_3)^2 \cdot \operatorname{rank}(q) = 2 \cdot \operatorname{Ker}(q) = \begin{cases} x_1 \\ x_2 \\ x_3 \end{pmatrix} \mid \begin{pmatrix} 1 & 1 & 1 \\ 1 & 2 & 3 \\ 1 & 3 & 5 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = 0 = \operatorname{Span}(\begin{pmatrix} 1 \\ -2 \\ 1 \end{pmatrix}).$$

2. (2,0).

3.
$$v = (x_1, x_2, x_3) \in G^{\perp}$$
 if: $(x_1 \ x_2 \ x_3) \begin{pmatrix} 1 & 1 & 1 \\ 1 & 2 & 3 \\ 1 & 3 & 5 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} = x_1 + 2x_2 + 3x_3 = 0$, and $(x_1 \ x_2 \ x_3) \begin{pmatrix} 1 & 1 & 1 \\ 1 & 2 & 3 \\ 1 & 3 & 5 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} = x_1 + 2x_2 + 3x_3 = 0$. Thus $G^{\perp} = \text{Span} \begin{pmatrix} -2 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} -3 \\ 0 \\ 1 \end{pmatrix} = G \cap G^{\perp}$ so they are not in direct sum.



Exercise 13. Determine the signature of the quadratic form $q \in \mathscr{Q}(\mathbb{R}^n)$ whose matrix in the canonical basis of \mathbb{R}^n is given by

$$(\min(i,j))_{1 \le i,j \le n} = \begin{pmatrix} 1 & 1 & 1 & \cdots & 1 \\ 1 & 2 & 2 & \cdots & 2 \\ 1 & 2 & 3 & \cdots & 3 \\ \vdots & \vdots & \vdots & & \vdots \\ 1 & 2 & 3 & \cdots & n \end{pmatrix}$$

Solution of exercise 13. Hint: Write it as sum of rank 1 matrices and use Exercise 3.